



# Introduction to JPL's GPS Time Series

*Edited Time Series, Velocity Field, and Web Site*

M. Heflin

*Point Positions*

A. Moore

*Orbits and Clocks*

D. Murphy, S. Desai, W. Bertiger, B. Haines, D. Kuang, A. Sibthorpe,  
A. Sibois, P. Ries, D. Hemberger, A. Dietrich

The research described herein was performed at the Jet Propulsion Laboratory of the California Institute of Technology, under a contract with the National Aeronautics and Space Administration. Government sponsorship acknowledged. Copyright 2018 © California Institute of Technology.



# GPS Time Series - Four Basic Steps

---

## **Step 1 – Orbits and Clocks**

- Get data from roughly eighty global GPS receivers
- Compute precise GPS orbits and clocks in NNR GPS reference frame
- Compute transformation parameters from NNR GPS frame to IGS14

## **Step 2 - Point Positions**

- Compute point positions for thousands of global GPS receivers in NNR GPS reference frame
- Resolve phase ambiguities
- Apply transformation parameters to obtain positions in IGS14

## **Step 3 – Time Series**

- Search for breaks
- Remove outliers
- Estimate positions, velocities, breaks, and seasonal parameters

## **Step 4 – Web Site**

- Create tables and plots which are posted on the web site
- Create edited time series and residuals which can be downloaded



# Step 1 – Orbits and Clocks

---

## **Input Data**

Daily rinex files from roughly eighty global GPS receivers

## **Fit Parameters**

Satellite initial conditions

Satellite non-gravitational forces

Satellite clocks

Receiver tropospheric zenith delay and gradients

Receiver positions

Receiver clocks except for one reference clock

Polar motion and rate

UT rate

Resolved phase ambiguities

Transformation parameters from NNR GPS frame to IGS14

## **Models**

Gravity from Earth, Sun, Moon, and other planets

DE421 planetary ephemeris

GSPM10 satellite solar pressure model

IAU06 model for precession and nutation

IERS2010 tides

FES2004 ocean loading

IGS satellite and receiver antenna phase center models



## Step 2 - Point Positions

---

### **Input Data**

Daily rinex files for thousands of global GPS receivers

Satellite orbits from step 1

Satellite clocks from step 1

Phase ambiguities from step 1

Transformation parameters from step 1

### **Fit Parameters**

Receiver tropospheric zenith delay and gradients

Receiver position

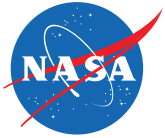
Receiver clocks

Resolved phase ambiguities

### **Reference Frame**

NNR orbits and clocks are used for point positioning

Transformation parameters from step 1 are applied to obtain position estimates in IGS14



## Step 3 - Time Series

---

### **Input data**

Daily GPS point positions

### **Fit Parameters**

Receiver positions

Receiver velocities

Receiver breaks

Receiver seasonals

### **Breaks**

CHI<sup>2</sup> is computed with and without each break candidate and those with  $F > 150$  are accepted

$$F = \frac{[\text{Chi}^2(\text{without}) - \text{Chi}^2(\text{with})]}{\text{Chi}^2(\text{with})} * \frac{[\text{ndata} - \text{pwith}]}{[\text{pwith} - \text{pwithout}]}$$

ndata is the number of position observations being fit

pwith is the number of parameters with the break included

pwithout is the number of parameters without the break included

### **Outliers**

Points with formal errors  $> 10$  mm in any component

### **Error Scaling**

Parameter errors multiplied by 20 to make them consistent with one sigma data decimation results



# Step 4 - Web Site

## Web Launch date

November 29, 1994

## Implementation

HTML

KML

Javascript

## Interface

Google map

List of sites

## Tables

Positions

Velocities

Breaks

Seasonals

Methods

## Download

Time series

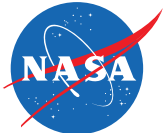
Residuals

# GPS Time Series

The Global Positioning System (GPS) is a constellation of 30 satellites which is used for navigation and precise geodetic position measurements. Data from over 2000 receivers have been analyzed at the Jet Propulsion Laboratory, California Institute of Technology under contract with the National Aeronautics and Space Administration. JPL's [GipsyX software](#) is used to produce these time series and other useful data products. Horizontal velocities, mostly due to motion of the Earth's tectonic plates, are represented on the map by lines extending from each site. Click on a dot or name to see detailed time series for a particular site. Additional information may be obtained from [mbh@jpl.nasa.gov](mailto:mbh@jpl.nasa.gov).

[Geodetic Positions](#) || [Cartesian Positions](#) || [Velocities](#)  
[Break Estimates](#) || [Seasonal Estimates](#)  
[Time Series](#) || [Residuals](#)  
[Methods](#)





# Formats and Plots

## Time Series and Residual Format

Column 1: Decimal\_YR

Columns 2-4: East(m) North(m) Vert(m)

Columns 5-7: E\_sig(m) N\_sig(m) V\_sig(m)

Columns 8-10: E\_N\_cor E\_V\_cor N\_V\_cor

Column 11: Time in Seconds past J2000

Columns 12-17: Time in YEAR MM DD HR MN SS

## Observations

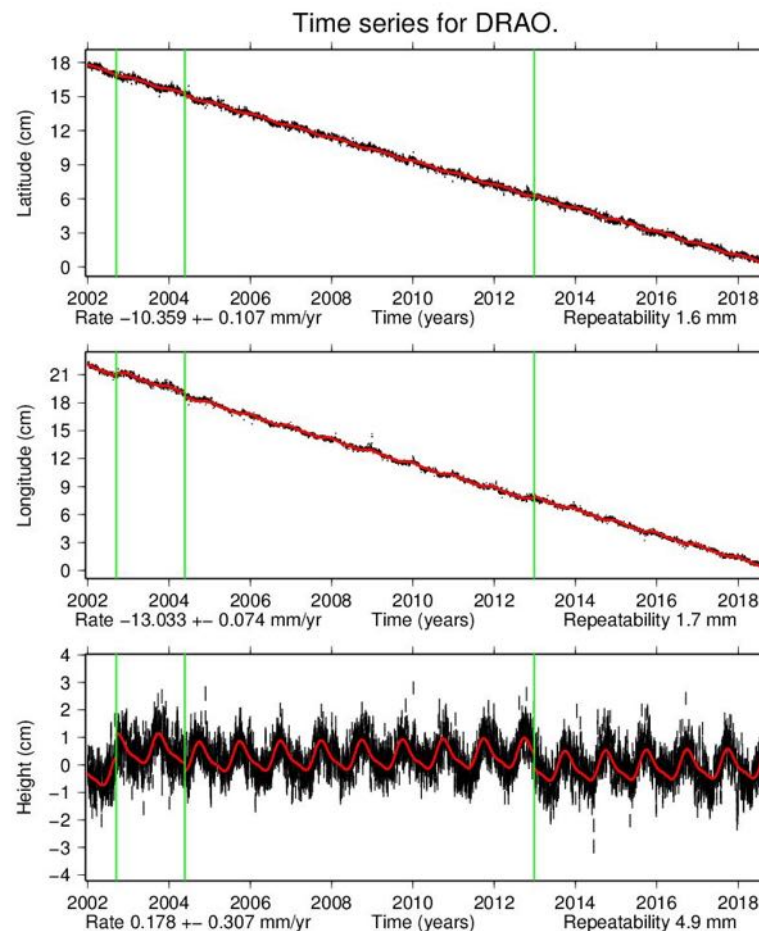
Black points with error bars

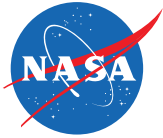
## Fit

Red points

## Breaks

Green bars





# Download Instructions

---

## **Download edited time series for a single site**

Click "Time Series" on web site  
Right click site of interest  
Choose "Download Linked File"

## **Download residual time series for a single site**

Click "Residuals" on web site  
Right click site of interest  
Choose "Download Linked File"

## **Download all edited time series**

```
wget -r -nd -np -R "index.html*" -A "*.series"  
"https://sideshow.jpl.nasa.gov/pub/JPL_GPS_Timeseries/repro2018a/post/point" .
```

## **Download all residual time series**

```
wget -r -nd -np -R "index.html*" -A "*.resid"  
"https://sideshow.jpl.nasa.gov/pub/JPL_GPS_Timeseries/repro2018a/post/resid" .
```